

Daeho Kim

Integrated MS-PhD student, Kyung Hee University, Korea Republic of.

✉ kdh2769@khu.ac.kr

☎ (+82) 10 9886 2714

🌐 Daehow

📺 AIRLAB

👤 Research Interest

My primary research interest lies in **Embodied AI**. I have been focusing on foundational research to develop autonomous robots and aspire to conduct meaningful research towards a world where humans and robots coexist harmoniously.

🎓 Education

Kyung Hee University

M.S. - Ph.D in Software Convergence

Gyeonggi-do Korea

Sep. 2023 - Present

Kyung Hee University, Republic of Korea

B.S. in Software Convergence

Gyeonggi-do Korea

Mar. 2018 - Aug. 2023

- Majored in Robot & Vision Track
- Leave on absence due to military service (Jan. 2019 - Aug. 2020)
Assistant Instructor, Ranger Training Unit, Republic of Korea Army Infantry School

📖 Publications

International papers

- [1] GAIA: Generating Task Instruction Aware Simulation Grounded in Real Contexts using Vision-Language Models
IEEE Robotics and Automation Letters (RA-L) 2025.
Dogyu Ko†, Chanyoung Yeot†, **Daeho Kim**, Jaeho Kim and Hyoseok Hwang*
- [2] Camera-LiDAR Extrinsic Calibration using Constrained Optimization with Circle Placement
IEEE Robotics and Automation Letters (RA-L) Vol. 10, Issue:2, pp. 883-890, 2025.
(Presentation at ICRA 2025 in Atlanta)
Daeho Kim, Seunghui Shin and Hyoseok Hwang*
- [3] PAIR360: A Paired Dataset of High-Resolution 360° Panoramic Images and LiDAR Scans
IEEE Robotics and Automation Letters (RA-L) Vol. 9, Issue:11, pp. 9550-9557, 2024.
(Presentation at ICRA 2025 in Atlanta)
Geunu Kim, **Daeho Kim**, Jaeyun Jang, and Hyoseok Hwang*
- [4] Moving End-Effectors by Deep Reinforcement Learning for Better Hand-Eye Calibration Performance
under review, 2025
Seunghui Shin, **Daeho Kim**, and Hyoseok Hwang*

Domestic papers

- [1] Performance Validation of Target-based Camera-LiDAR Extrinsic Calibration on Simulation
Summer Annual Conference of KIBME (special session), 2024
Daeho Kim, and Hyoseok Hwang*

🏠 Projects

Pick and Place system with 6-DOF Pose Estimation using DOPE



- Pick and Place / 6-DOF Pose estimation / Domain Generalization

Camera-LiDAR Extrinsic Calibration using an Ordinary Box



- Extrinsic Calibration / Sequential-RANSAC

Stereo RGB camera 3D reconstruction



- Stereo Calibration / 3D Reconstruction

Turtlebot Manipulation with Optical Flow in Gazebo Simulation



- Optical Flow / Teleoperation

Academic Experience

Teaching Assistant | Kyung Hee University

Gyeonggi-do Korea

- 3D Data Processing (SWCON36600)
- Robot Programming (SWCON33100)

Spring Sem. 2024.
Fall Sem. 2023.

Silicon Valley Software Program | San Jose State University

California USA

- Silicon valley software innovation & Technology contest

Jan. 2021 - Feb. 2021

Skills

- Sensors - LiDAR, 360° camera, Fisheye camera, RGB-D camera, GPS, IMU
- Programming - Python, C/C++
- Simulator - Gazebo, IsaacSim
- Frameworks - ROS, Open3D, OpenCV, PCL, PyTorch

Languages

 Korean - Native

 English - Business Competence